

October 31, 2019

Short Answers (25 Points)

1. Consider the model

$$y_{it} = x'_{it}\beta + \eta_i + v_{it}$$

where $i = 1, \dots, N$ and $t = 1, \dots, T$. Using the notation from class, suppose that

$$\begin{aligned}\eta_i | X_i &\sim N(0, \sigma_\eta^2) \\ v_i | X_i &\sim N(0, \sigma^2 I_T)\end{aligned}$$

and that η_i and v_i are independent of one another. What is the GLS weighting matrix?

2. SOLS of a system is the same as FGLS under certain conditions. What are they?
3. Consider the $G \times 1$ system

$$y_i = X_i\beta + u_i$$

where X_i is $K \times G$. Suppose that we estimate $\Omega \equiv E[u_i u_i']$ with

$$\hat{\Omega} \equiv \frac{1}{N} \sum_{i=1}^N \hat{u}_i \hat{u}_i'$$

where the residuals are constructed based on a (consistent) SOLS first-stage estimate. Show that

$$\frac{1}{N} \sum_{i=1}^N X_i' \hat{\Omega}^{-1} X_i = \frac{1}{N} \sum_{i=1}^N X_i' \Omega^{-1} X_i + o_p(1)$$

4. Let $X \sim U[0, 1]$. For a draw $X = x$, we define $Y \sim U[0, x]$. What is the marginal distribution of Y ?
5. Let X and Y be continuous independent random variables with respective CDF's given by F and G . Define $U \equiv F(X)$ and $V \equiv G(Y)$ and $W \equiv UV$. What is the CDF of W ?

Long Answers (75 Points)

1. Consider a system of T equations given by

$$y_i = X_i\beta + \eta_i i + v_i$$

where $y_i = (y_{i1}, \dots, y_{iT})'$ is $T \times 1$, $X_i = (x_{i1}, \dots, x_{iT})'$ is $T \times K$, $v_i = (v_{i1}, \dots, v_{iT})'$ is $T \times 1$, and i is a $T \times 1$ vector of ones. Assume that

$$\begin{aligned} E[v_i|X_i] &= 0 \\ V[v_i|X_i] &= \Omega. \end{aligned}$$

- (a) Suppose that you are concerned that η_i might be correlated with X_i . Write down an estimator that addresses this problem. Do not use Ω in your estimator.

Assume that η_i is a potential problem for (b)-(e).

- (b) If we know what Ω is, write down an estimator that is more efficient than the estimator from (a).
- (c) Derive the asymptotic distributions for the SOLS and GLS estimators from (a) and (b).
- (d) Derive the weighting matrix for the efficient GLS estimator when

$$\begin{aligned} v_{it} &= \varepsilon_{it} - \theta\varepsilon_{i(t-1)} \text{ for } t > 1 \\ v_{i1} &= \varepsilon_{i1}. \end{aligned}$$

and the ε_{it} are white noise with variance equal to σ^2 .

- (e) Suppose that we computed the GLS estimator under the (false) assumption that $V[v_i|X_i] = \Omega$. So, in actuality, we have that $V[v_i|X_i] = \Sigma \neq \Omega$. What is the asymptotic distribution of the GLS estimator now? Is it efficient?

2. Consider the model

$$y_{it} = x'_{it}\beta + \eta_i + v_{it}$$

where x_{it} is a $k \times 1$ vector and η_i is unobserved where $i = 1, \dots, N$ and $t = 1, \dots, T$. Suppose that T is large but N is fixed, so that our asymptotics will be with respect to T . In addition, suppose that for a given i , the v_{it} are stationary and ergodic.

- (a) Write the model as a system of N equations of the form

$$y_t = W_t\delta + v_t.$$

Define y_t , W_t , δ and v_t in terms of the model's variables and parameters and be explicit about the dimensions and definitions of each of the vectors.

- (b) Write down an estimator of δ and provide a moment condition such that it is consistent.

(c) How would you estimate the standard errors of your estimator?

3. Consider the model:

$$y_{it} = \eta_i + \rho_i \times t + x'_{it}\beta + u_{it}$$

where $i = 1, \dots, N$ and $t = 1, \dots, T$. Define $X_i \equiv (x_{i1}, \dots, x_{iT})'$, $T \equiv (1, \dots, T)'$, $y_i \equiv (y_{i1}, \dots, y_{iT})$, $u_i \equiv (u_{i1}, \dots, u_{iT})$, and i to be a $T \times 1$ vector of ones. Assume that $E[u_i|X_i] = 0$ and $V[u_i|X_i] = \sigma^2 \mathbf{I}_T$.

- (a) Write the model as a $T \times 1$ system using the definitions given above.
- (b) With the existing assumptions, provide two reasons why OLS of y_i onto X_i might be inconsistent.
- (c) Provide definitions of a $(T-1) \times T$ and $(T-2) \times (T-1)$ first difference matrices. Call these D_1 and D_2 , respectively.
- (d) Using D_1 and D_2 to transform the system in part (a), provide an estimator that is robust to endogeneity concerns raised in part (b).
- (e) Is the estimator in part (d) efficient? If so, why is it? If not, provide an estimator based off of it that is efficient.